Lecture 10. The Perceptron

COMP90051 Statistical Machine Learning

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This lecture

- Perceptron model
 - Introduction to Artificial Neural Networks
 - * The perceptron model
- Perceptron training rule
 - Stochastic gradient descent
- Kernel perceptron

The Perceptron Model

A building block for artificial neural networks, yet another linear classifier

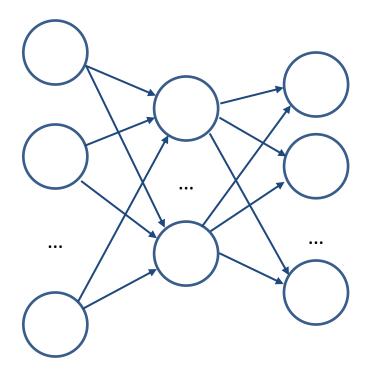
Biological inspiration

- Humans perform well at many tasks that matter
- Originally neural networks were an attempt to mimic the human brain



Artificial neural network

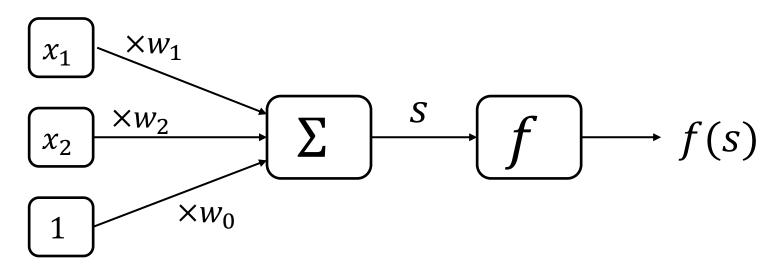
- As a crude approximation, the human brain can be thought as a mesh of interconnected processing nodes (neurons) that relay electrical signals
- Artificial neural network is a network of processing elements
- Each element converts inputs to output
- The output is a function (called activation function) of a weighted sum of inputs



Outline

- In order to use an ANN we need (a) to design network topology and (b) adjust weights to given data
 - * In this subject, we will exclusively focus on task (b) for a particular class of networks called feed forward networks
- Training an ANN means adjusting weights for training data given a pre-defined network topology
- First we will turn our attention to an individual network element, before building deeper architectures

Perceptron model



Compare this model to logistic regression

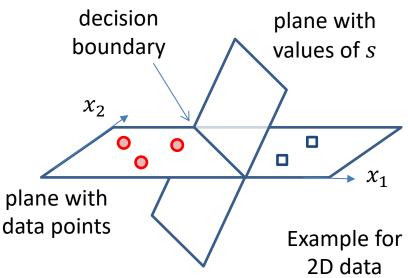
- x_1 , x_2 inputs
- w_1 , w_2 synaptic weights
- w_0 bias weight
- f activation function

Perceptron is a linear binary classifier

Perceptron is a binary classifier:

Predict class A if $s \ge 0$ Predict class B if s < 0where $s = \sum_{i=0}^{m} x_i w_i$

Perceptron is a <u>linear classifier</u>: *s* is a linear function of inputs, and the decision boundary is linear



Exercise: find weights of a perceptron capable of perfect classification of the following dataset

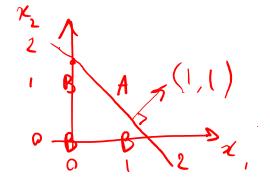
x_1	x_2	y
0	0	Class B
0	1	Class B
1	0	Class B
1	1	Class A



Exercise: find weights of a perceptron capable of perfect classification of the following dataset

$V_1 = W_2 = 1$
Wo = -1.5
$S = x_1 + x_2 - 1.5$

x_1	x_2	y	5
0	0	Class B	-1.5
0	1	Class B	- O. S
1	0	Class B	-0.5
1	1	Class A	0.5



art: OpenClipartVectors
 at pixabay.com (CC0)



Mini Summary

- Perceptron
 - Introduction to Artificial Neural Networks
 - * The perceptron model

Next: Perceptron training

Perceptron Training Rule

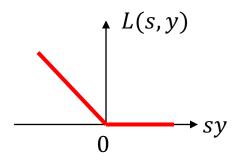
Gateway to stochastic gradient descent. Convergence guaranteed by convexity.

Loss function for perceptron

- "Training": finds weights to minimise some loss. Which?
- Our task is binary classification. Encode one class as +1 and the other as -1. So each training example is now $\{x, y\}$, where y is either +1 or -1
- Recall that, in a perceptron, $s = \sum_{i=0}^{m} x_i w_i$, and the sign of s determines the predicted class: +1 if s > 0, and -1 if s < 0
- Consider a single training example.
 - * If y and s have same sign then the example is classified correctly.
 - st If y and s have different signs, the example is misclassified

Loss function for perceptron

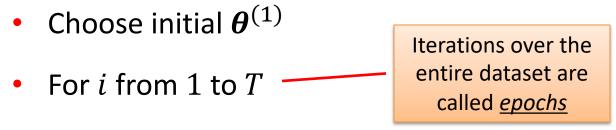
- The perceptron uses a loss function in which there is no penalty for correctly classified examples, while the penalty (loss) is equal to s for misclassified examples*
- Formally:
 - * L(s, y) = 0 if both s, y have the same sign
 - * L(s, y) = |s| if both s, y have different signs
- This can be re-written as $L(s, y) = \max(0, -sy)$



^{*} This is similar, but not identical to the SVM's loss function: the *hinge loss*

Stochastic gradient descent

• Randomly shuffle/split all training examples in B batches



- For j from 1 to B
- Do gradient descent update <u>using data from batch j</u>

 Advantage of such an approach: computational feasibility for large datasets

Perceptron training algorithm

Choose initial guess $\mathbf{w}^{(0)}$, k=0

For i from 1 to T (epochs)

For j from 1 to N (training examples)

Consider example $\{x_j, y_j\}$

$$\underline{\mathsf{Update}}^*: \boldsymbol{w}^{(k++)} = \boldsymbol{w}^{(k)} - \eta \nabla L(\boldsymbol{w}^{(k)})$$

$$L(\mathbf{w}) = \max(0, -sy)$$

$$s = \sum_{i=0}^{m} x_i w_i$$

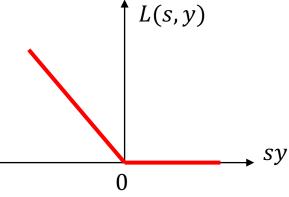
$$\eta \text{ is learning rate}$$

*There is no derivative when s=0, but this case is handled explicitly in the algorithm, see next slides

Perceptron training rule

- We have $\frac{\partial L}{\partial w_i} = 0$ when sy > 0
 - * We don't need to do update when an example is correctly classified
- We have $\frac{\partial L}{\partial w_i} = -x_i$ when y = 1 and s < 0
- We have $\frac{\partial L}{\partial w_i} = x_i$ when y = -1 and s > 0

• $s = \sum_{i=0}^{m} x_i w_i$



Perceptron training algorithm

When classified correctly, weights are unchanged

When misclassified:
$$\mathbf{w}^{(k+1)} \models -\eta(\pm \mathbf{x})$$

($\eta > 0$ is called *learning rate*)

$$\begin{array}{ll} \underline{\text{If } y = 1, \, \text{but } s < 0} & \underline{\text{If } y = -1, \, \text{but } s \geq 0} \\ w_i \leftarrow w_i + \eta x_i & w_i \leftarrow w_i - \eta x_i \\ w_0 \leftarrow w_0 + \eta & w_0 \leftarrow w_0 - \eta \end{array}$$

Convergence Theorem: if the training data is linearly separable, the algorithm is guaranteed to converge to a solution. That is, there exist a finite K such that $L(\mathbf{w}^K) = 0$

Perceptron convergence theorem

Assumptions

- * Linear separability: There exists \mathbf{w}^* so that $y_i(\mathbf{w}^*)'\mathbf{x}_i \geq \gamma$ for all training data $i=1,\ldots,N$ and some positive γ .
- * Bounded data: $||x_i|| \le R$ for i = 1, ..., N and some finite R.

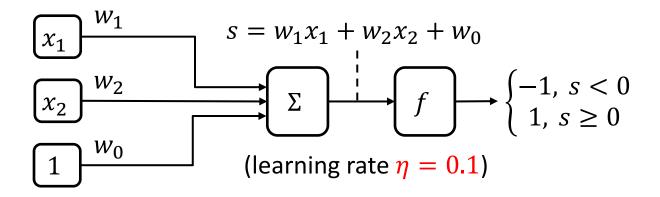
Proof sketch

- * Establish that $(w^*)'w^{(k)} \ge (w^*)'w^{(k-1)} + \gamma$
- * It then follows that $(w^*)'w^{(k)} \ge k\gamma$
- * Establish that $\|\boldsymbol{w}^{(k)}\|^2 \leq kR^2$
- * Note that $\cos(w^*, w^{(k)}) = \frac{(w^*)'w^{(k)}}{\|w^*\|\|w^{(k)}\|}$
- * Use the fact that $cos(...) \le 1$
- * Arrive at $k \leq \frac{R^2 ||w^*||^2}{\gamma}$

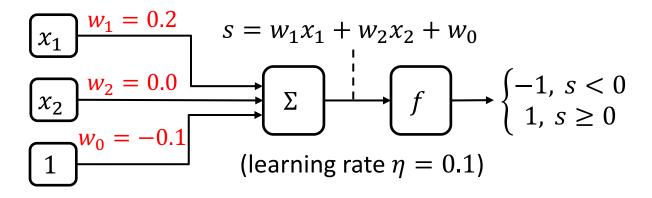
Pros and cons of perceptron learning

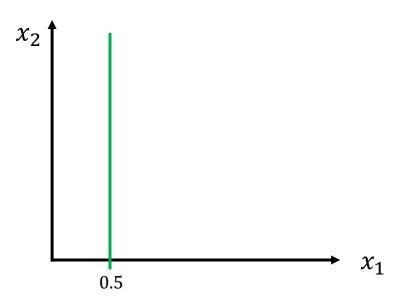
- If the data is linearly separable, the perceptron training algorithm will converge to a correct solution
 - * There is a formal proof ← good!
 - ★ It will converge to some solution (separating boundary), one of infinitely many possible ← bad!
- However, if the data is not linearly separable, the training will fail completely rather than give some approximate solution
 - * Ugly 🕾

Basic setup

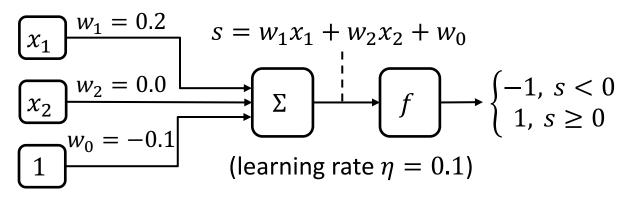


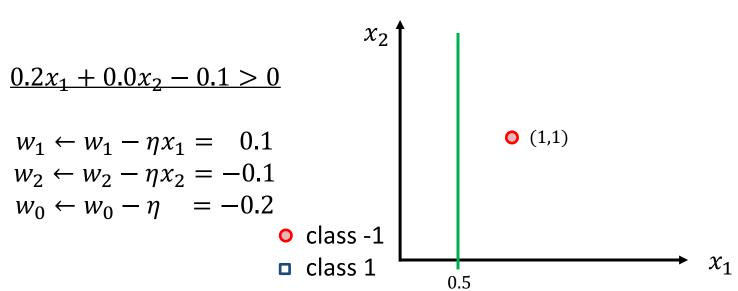
Start with random weights



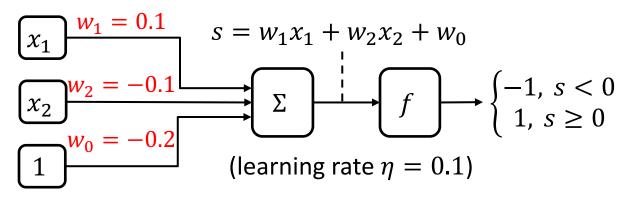


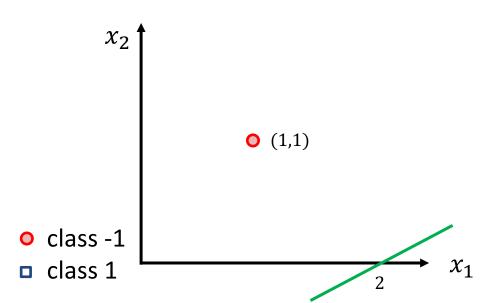
Consider training example 1



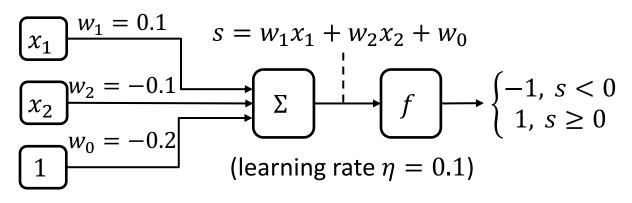


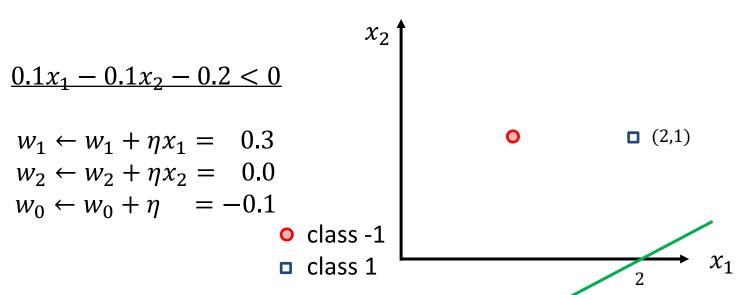
Update weights



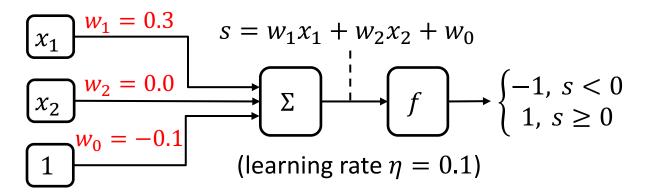


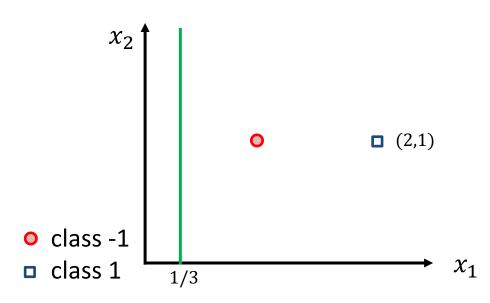
Consider training example 2



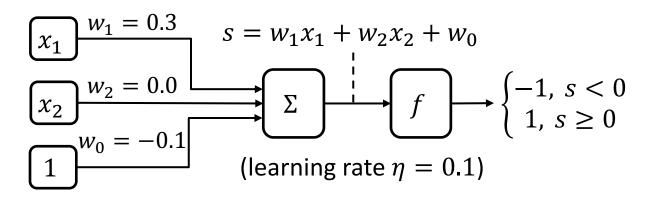


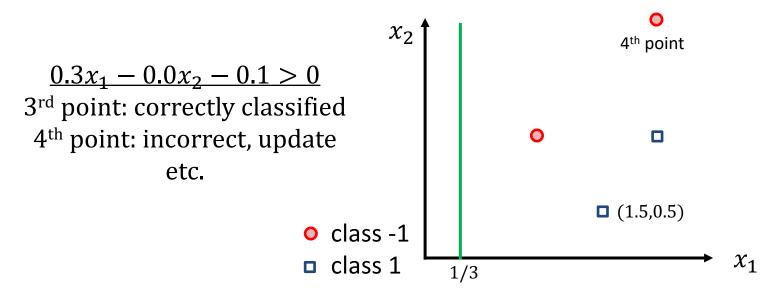
Update weights



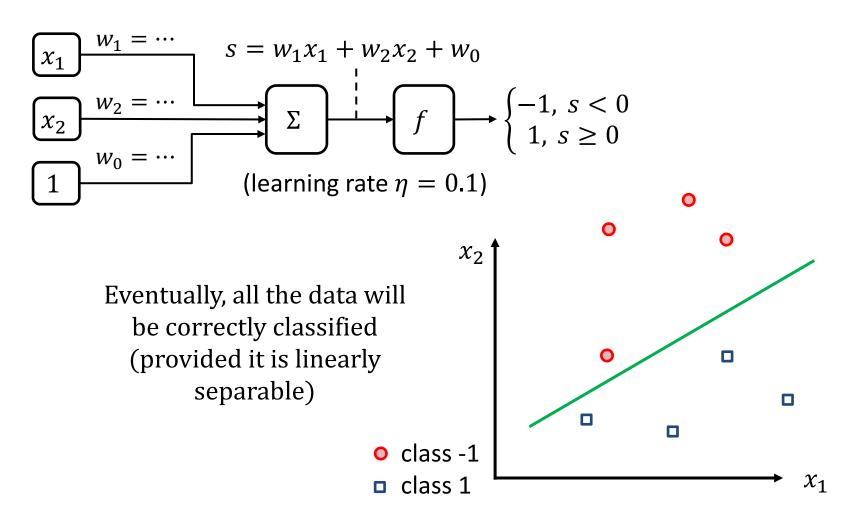


Further examples





Further examples



Mini Summary

- Perceptron loss function
- Stochastic gradient descent
- Perceptron training rule
 - Perceptron convergence theorem

Next: Kernel perceptron

Kernel Perceptron

Another example of a kernelizable learning algorithm (like the SVM).

Perceptron training rule: Recap

When classified correctly, weights are unchanged

When misclassified:
$$\mathbf{w}^{(k+1)} = -\eta(\pm \mathbf{x})$$

($\eta > 0$ is called *learning rate*)

$$\begin{array}{ll} \underline{\text{If } y = 1, \, \text{but } s < 0} & \underline{\text{If } y = -1, \, \text{but } s \geq 0} \\ w_i \leftarrow w_i + \eta x_i & w_i \leftarrow w_i - \eta x_i \\ w_0 \leftarrow w_0 + \eta & w_0 \leftarrow w_0 - \eta \end{array}$$

Suppose weights are initially set to 0

First update: $\mathbf{w} = \eta y_{i_1} \mathbf{x}_{i_1}$ Second update: $\mathbf{w} = \eta y_{i_1} \mathbf{x}_{i_1} + \eta y_{i_2} \mathbf{x}_{i_2}$ Third update $\mathbf{w} = \eta y_{i_1} \mathbf{x}_{i_1} + \eta y_{i_2} \mathbf{x}_{i_2} + \eta y_{i_3} \mathbf{x}_{i_3}$ etc.

Accumulating updates: Data enters via dot products

- Weights always take the form $\mathbf{w} = \sum_{i=1}^{n} \alpha_i y_i \mathbf{x}_i$, where $\boldsymbol{\alpha}$ some coefficients
- Perceptron weights always linear comb. of data!
- Recall that prediction for a new point x is based on sign of $w_0 + w'x$
- Substituting w we get $w_0 + \sum_{i=1}^n \alpha_i y_i x_i' x$
- The dot product $x_i'x$ can be replaced with a kernel

Kernelised perceptron training rule

Choose initial guess $\mathbf{w}^{(0)}$, k=0

Set $\alpha = 0$

For t from 1 to T (epochs)

For each training example $\{x_i, y_i\}$

Predict based on $w_0 + \sum_{j=1}^n \alpha_j y_j x_i' x_j$

If misclassified, update each $\alpha_j \leftarrow \alpha_j + \eta y_j$

Kernelised perceptron training rule

Choose initial guess $\mathbf{w}^{(0)}$, k=0

Set
$$\alpha = 0$$

For t from 1 to T (epochs)

For each training example $\{x_i, y_i\}$

Becomes kernel matrix k_{ii}

Predict based on $w_0 + \sum_{j=1}^n \alpha_j y_j K(\mathbf{x}_i, \mathbf{x}_j)$

If misclassified, update each $\alpha_j \leftarrow \alpha_j + \eta y_j$

Mini Summary

- Accumulating weight updates leads to linear combinations of data
- Predictions are dot products with data
- Can replace these with kernel evaluations
- Leads to kernel perceptron with kernel training rule

Next time: Deep learning